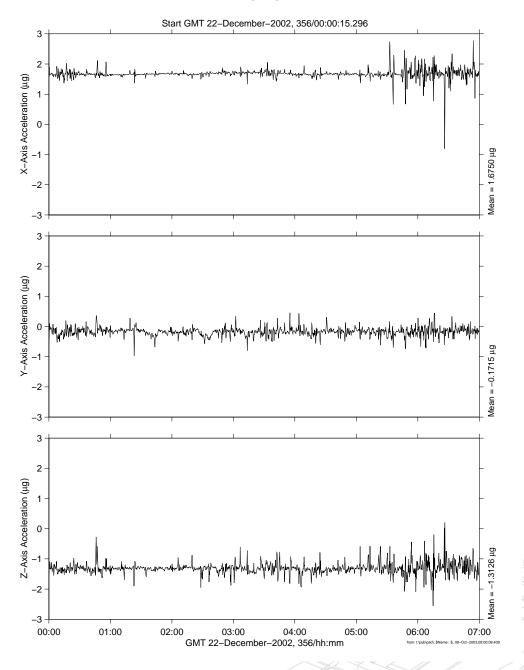
YVV ZLV TEA Attitude

mams, ossbtmf at LAB102, ER1, Lockers 3,4:[135.28 –10.68 132.12]

Increment: 6, Flight: 11A SSAnalysis[0.0 0.0 0.0]

+ZLV +YVV Torque Equilibrium Attitude







Microgravity Science Division

Glenn Research Center

PIMS ISS Acceleration Handbook Date last modified 10/14/03

Description		
Sensor	MAMS,ossbtmf 0.0625 sa/sec (0.01 Hz)	
Location	LAB1O2, ER1, Lockers 3,4	
Orientation	Space Station Analysis (SSA)	
Inc/Flight	Increment: 6, Flight: 11A	
Plot Type	Time Series	

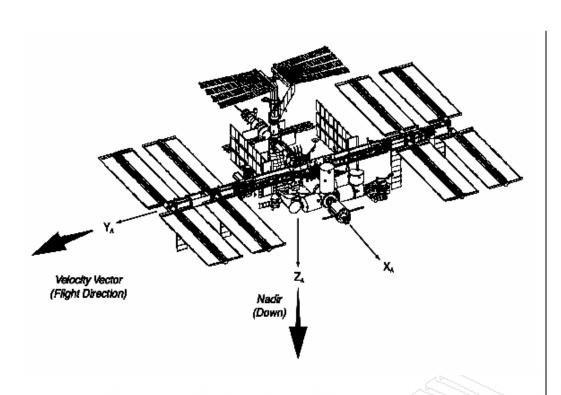
NOTES:

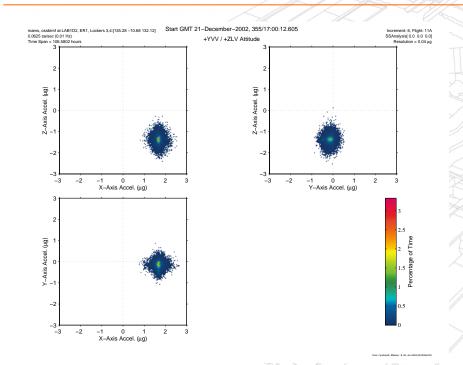
- YVV ZLV is a Torque equilibrium attitude (airplane-like) in which the Y-axis is maintained in the velocity vector and the Z-axis is pointing nadir. The ISS will fly with either the +Y-axis or -Y-axis in the forward direction. In this attitude the X-axis is perpendicular to orbital plane.
- During high solar beta angles (>60 degrees) the ISS is flown in YVV attitude to avoid overheating of the Progress batteries. For this reason, YVV has been referred to as "barbeque" mode.
- The plot shown is of data taken during a crew sleep period. The mean values per axis are tabulated below.

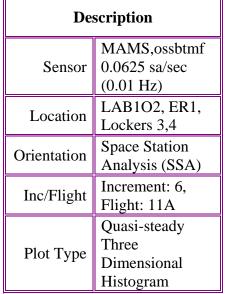
Axis	Mean (μg)	RMS (μg)
X	1.68	1.78
Y	-0.17	0.50
Z	-1.31	0.61

Regime:	Quasi-steady
Category:	Vehicle
Source:	Attitude, YVV

YVV ZLV TEA Attitude







NOTES:

- YVV attitude has been flown with either +Y or -Y axis into the velocity vector.
- Actual orientation dependent on ISS configuration. For time span of plot during Increment 6, attitude was nominally [yaw pitch roll] = [271.1 351.6 1.8]
- For the time period shown, the centroid is calculated as an estimate of the means for each axis. The results are tabulated below.

Axis	Centroid (µg)
/ X	1.70
Y	-0.15
Z	-1.34
Magnitude	2.17

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